

Assembly Instruction Manual

2015.08









TABLE OF CONTENT

SCREWS 1/1 SCALE	1
GLUE THE TUBES END'S	2
ATTACH YOUR MOTORS	3
ATTACH MOTOR MOUNTS ON ARMS	4
ROUTE YOUR MOTOR CABLES	5
FIX YOUR SIDE FRAME USING 2 SCREWS	5
SOLDER YOUR ESC'S	6
SLIDE ESC'S INTO THE TUBES	7
PRESS THE INSERTS IN POSITION	8
SLIDE YOUR FRAME SPACER AROUND THE TUBES	9
CHOOSE THE POSITION OF YOUR ARMS	10
SLIDE YOUR MOTOR SHAFTS INTO THE MOUNTING JIG	11
SOLDER YOUR ESC CABLES, EQUIPEMENTS CABLES TO YOUR BATTERY CONNECTOR CABLES	12
SCREW YOUR LOWER FRAME	12
FIX YOUR MOTOR MOUNT	13
SCREW THE THIRD SCREW	14
ATTACH YOUR Z SPACERS	15
CAMERA ANGLE	16
ADJUST MOTORS ANGLE	17
EQUIPMENTS LAYOUT	18
ATTACH YOUR CANOPY	19

SCREWS 1/1 SCALE

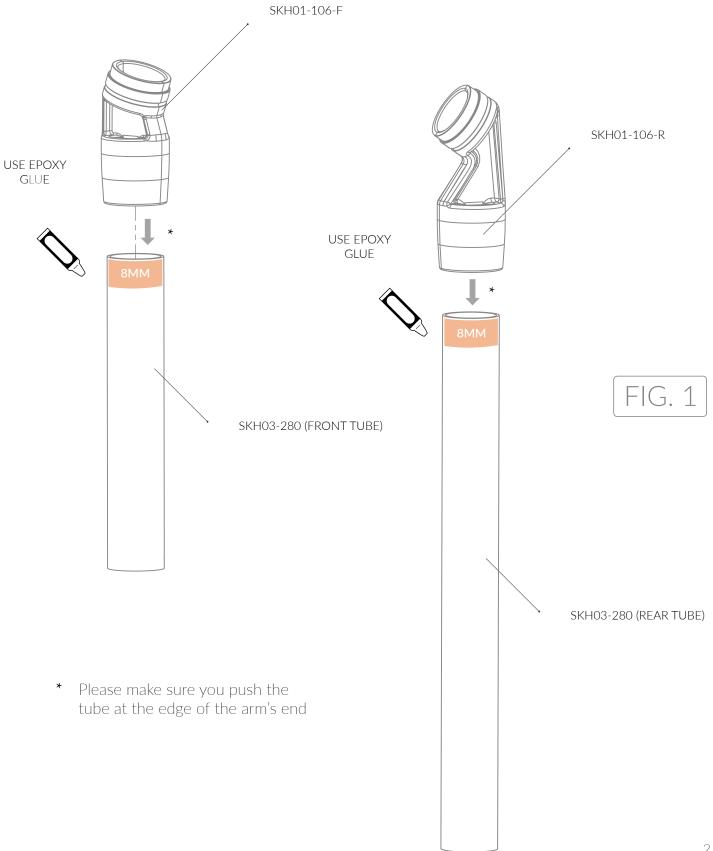
ISO 7380 M3X6

ISO 7380 M3X4 ISO 7380 M3X6TP ISO 7380 M3X8TP ISO 7380 M3X30 DIN 912 M2.5X8 HEX NUT M2.5

GLUE THE TUBES END'S

(Wipe out excess of glue with acetone)

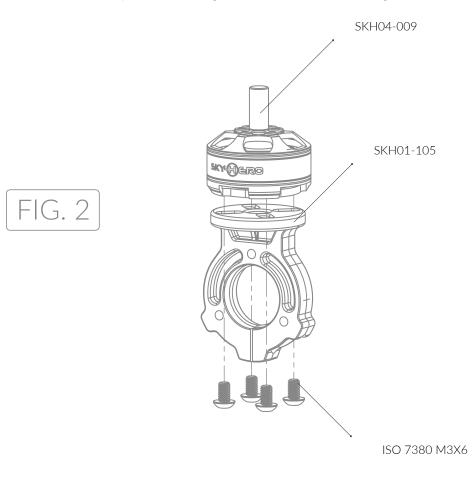


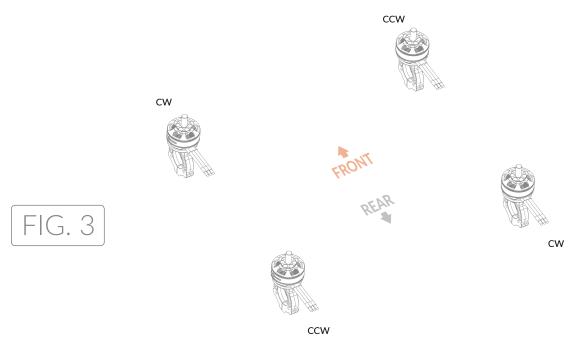


ATTACH YOUR MOTORS

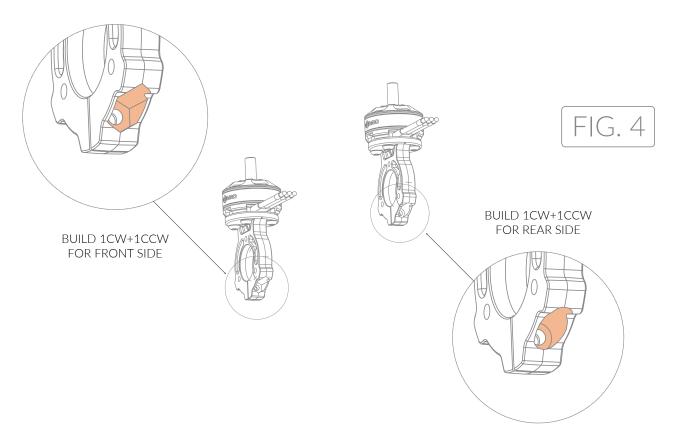
Warning! Before starting:

- Make sure to identify your clockwise (CW) and counter-clockwise (CCW) motors*.
- Be aware that all your wires will go backwards as shown in figure 3





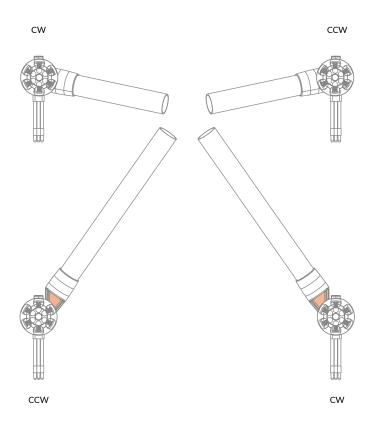
You must build 1CW+1CCW with the motors's wires oriented to the side of the nut for Anakin's front side and 1CW+1CCW with the motors's wires oriented to the side of the screw for Anakin's rear side



ATTACH MOTOR MOUNTS ON ARMS

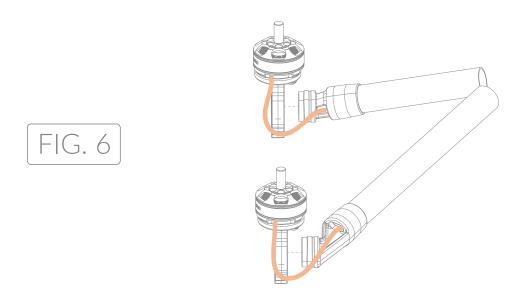
You must attach the motor mounts on arm's ends until you hear a **«clic»** noise.

 \triangle it can require quite an important pressure

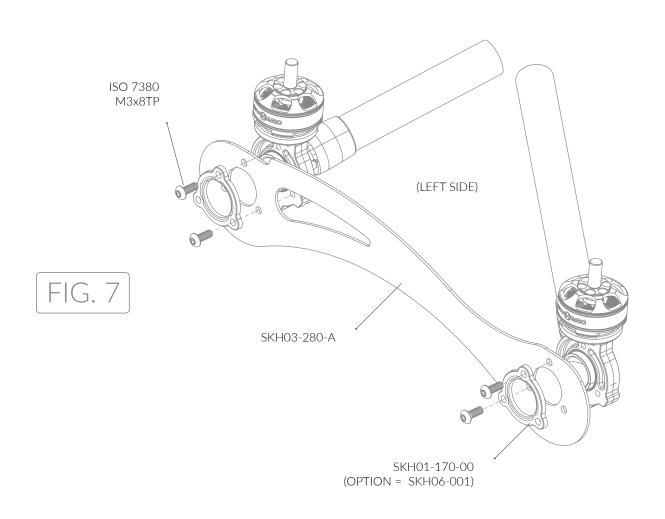


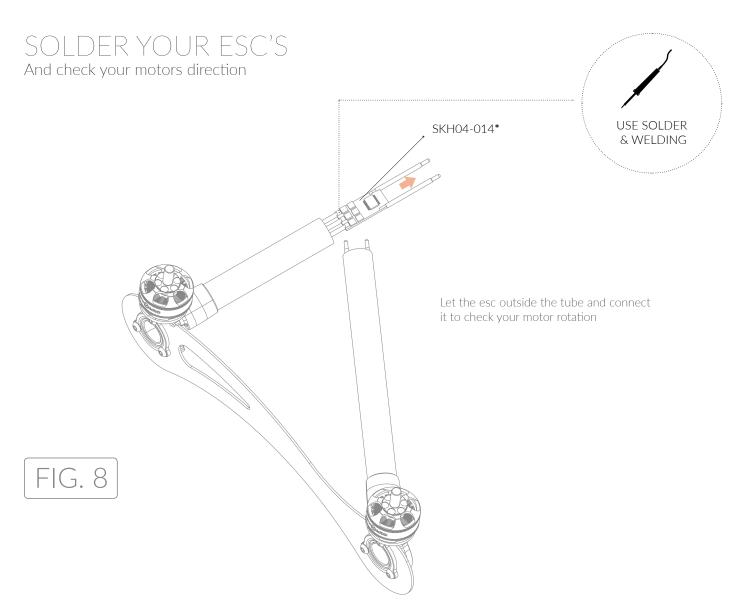
ROUTE YOUR MOTOR CABLES

Rear cables = 220mm long / Front cables = 150mm long



FIX YOUR SIDE FRAME USING 2 SCREWS Build left + right side

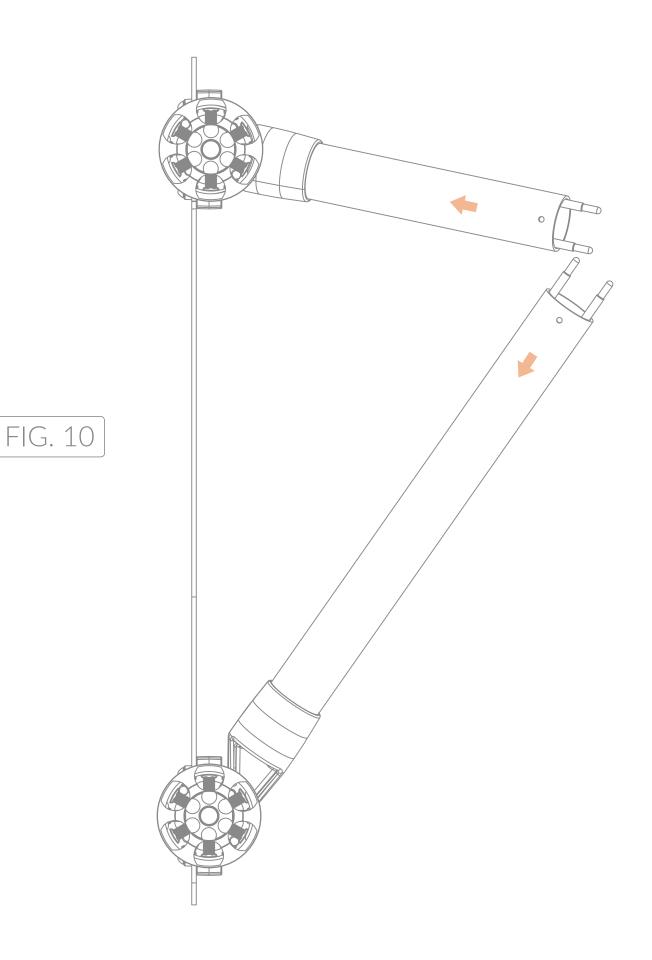






^{*} Optional parts

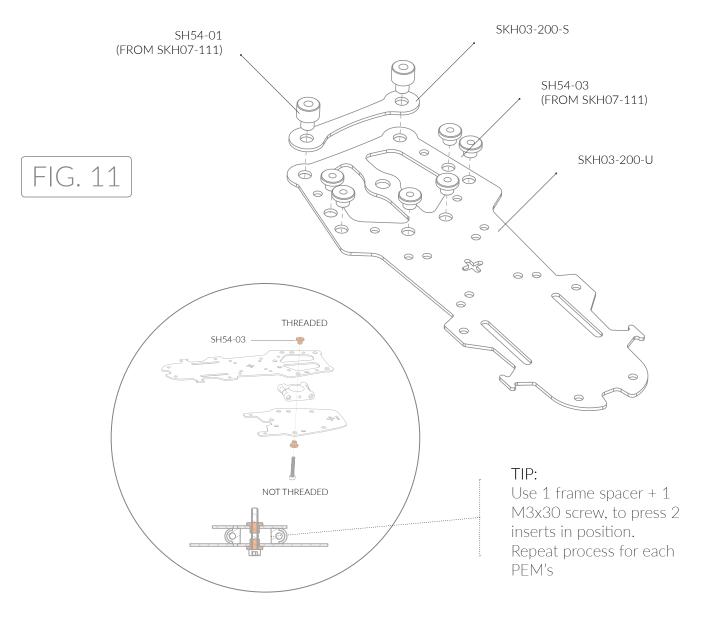
SLIDE ESC'S INTO THE TUBES

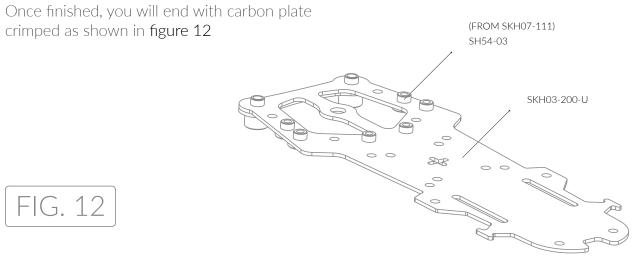


PRESS THE INSERTS IN POSITION

In order to mount the frame you must first interlock the PEM's by tightening them one by one until it's totally inserted in the carbon plate.

Use the threaded insert on upper frame.

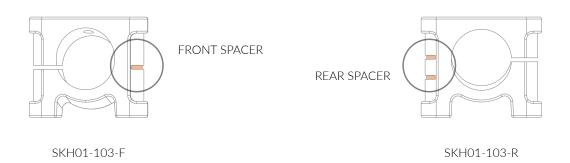


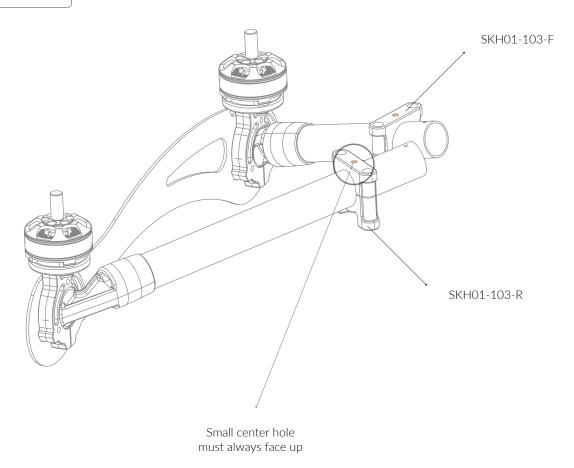


SLIDE YOUR FRAME SPACER AROUND THE TUBES

(Use the threaded insert on upper frame)

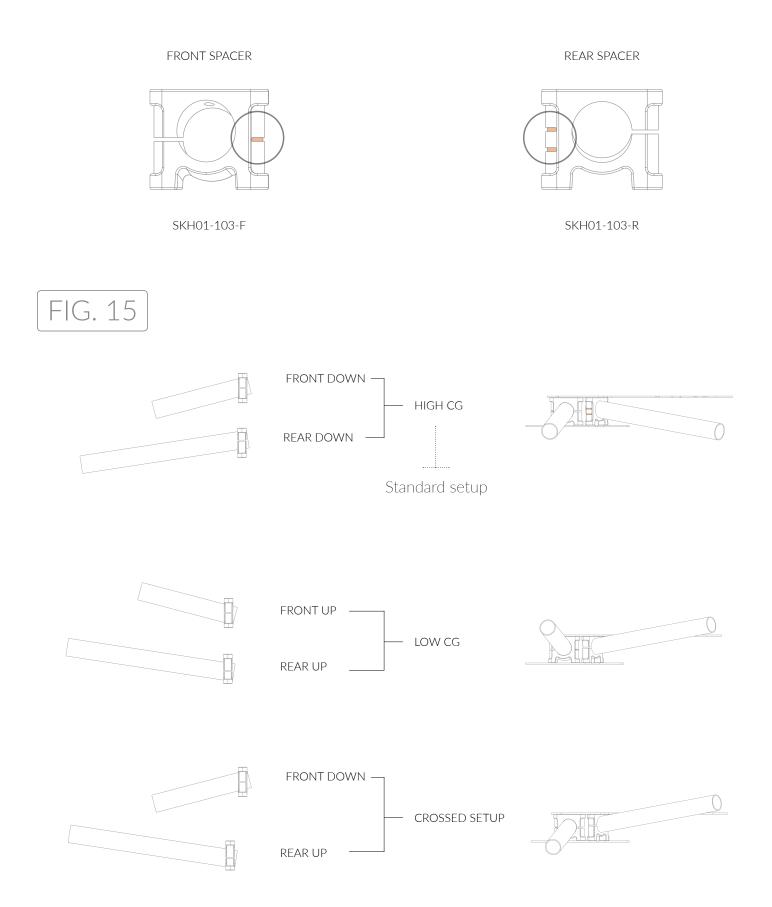
FIG. 13



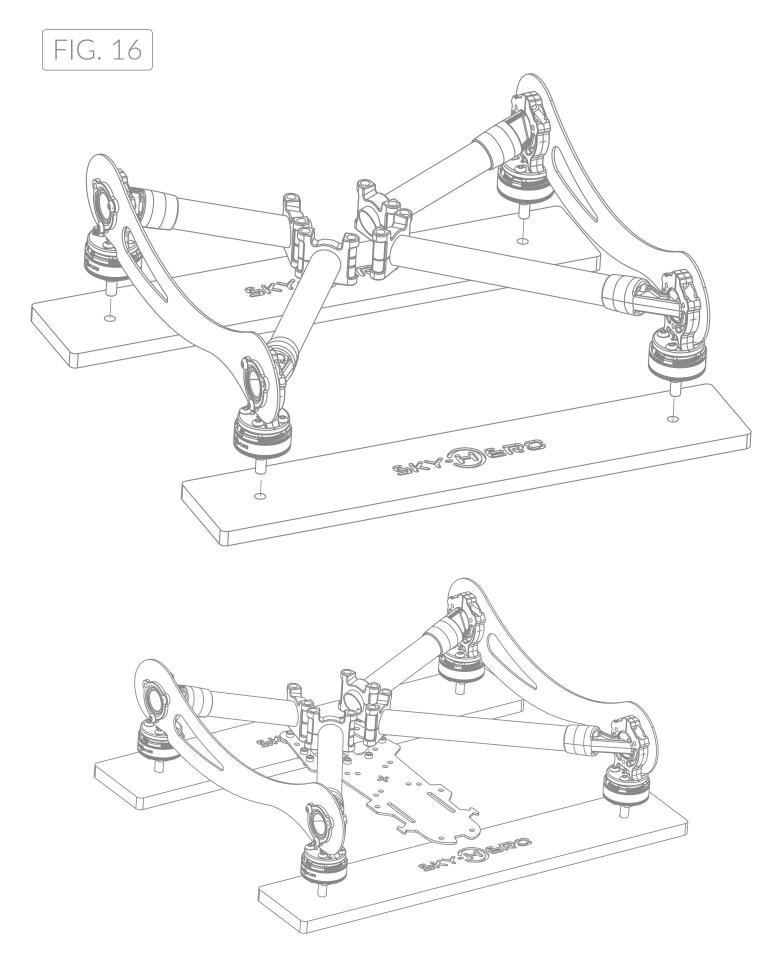


CHOOSE THE POSITION OF YOUR ARMS

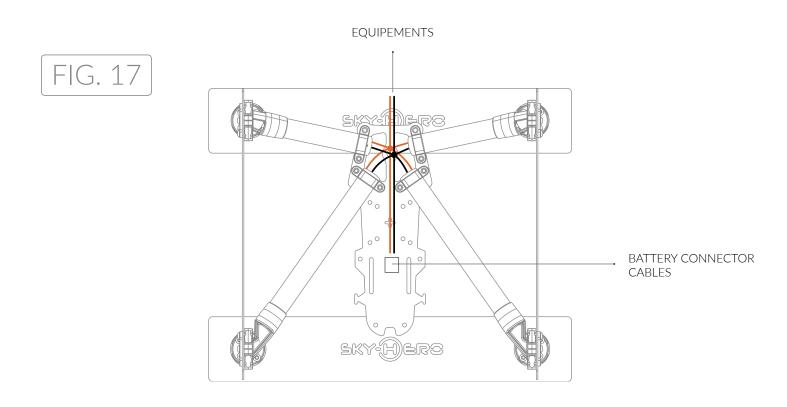
ACCORDING THE CENTER OF GRAVITY ADJUSTMENT YOU WANT



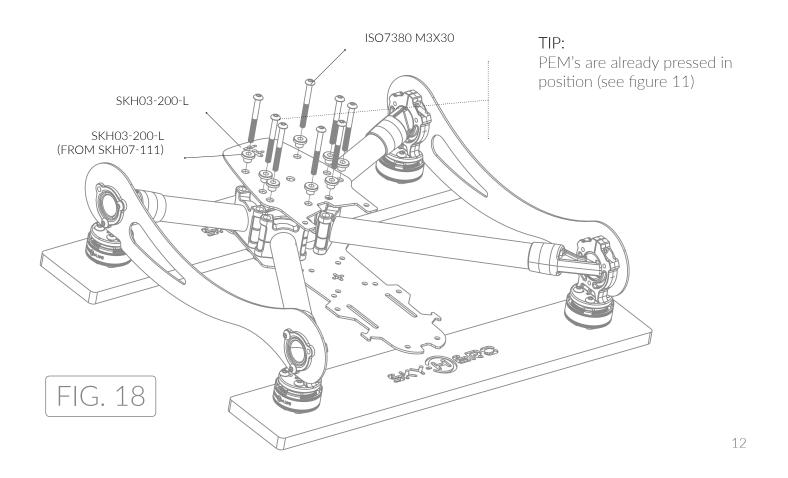
SLIDE YOUR MOTOR SHAFTS INTO THE MOUNTING JIG

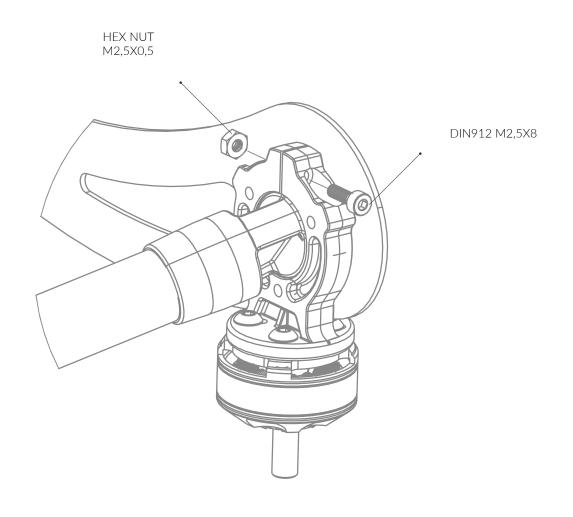


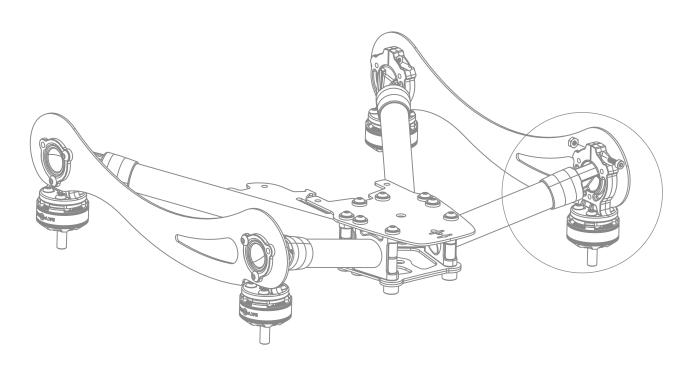
SOLDER YOUR ESC CABLES, EQUIPEMENTS CABLES, (VTX, UBEC, LED, ETC...) TO YOUR BATTERY CONNECTOR CABLES



SCREW YOUR LOWER FRAME (DO NOT OVERTIGHT)







SCREW THE THIRD SCREW

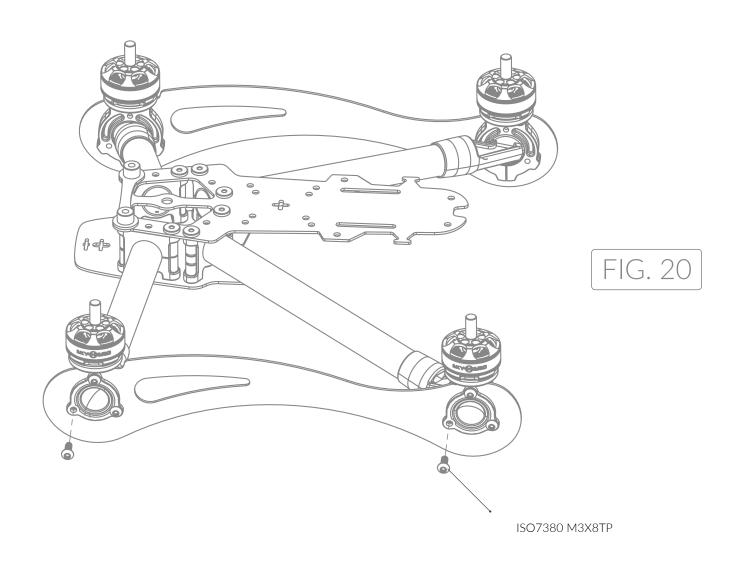
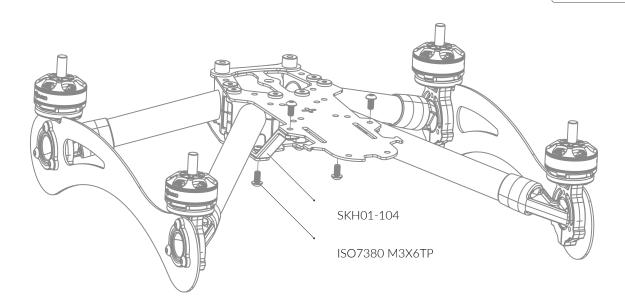
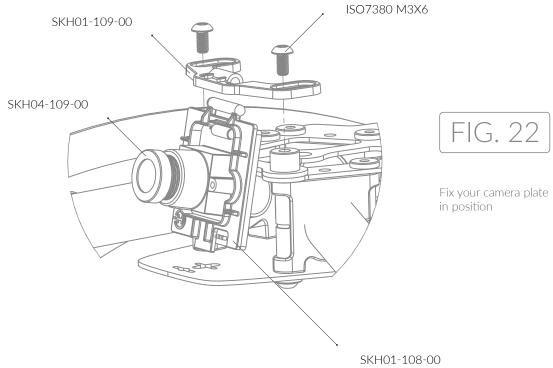
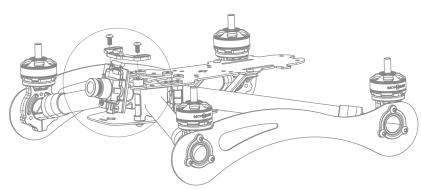


FIG. 21

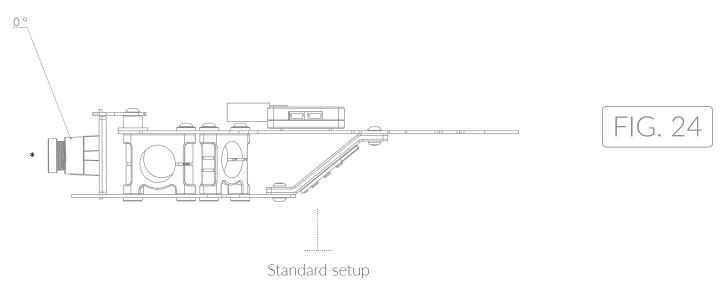






CAMERA ANGLE

YOU CAN ADJUST THE **ANGLE OF THE CAMERA** AS FOLLOWED



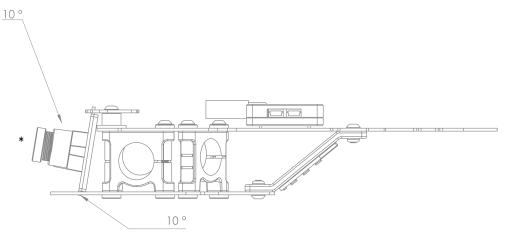
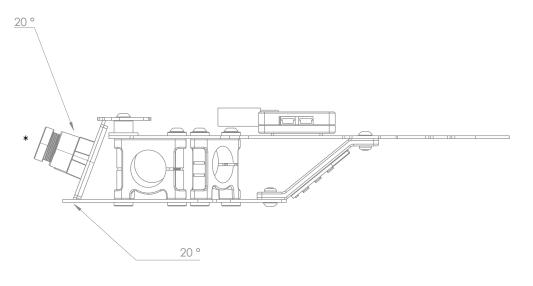


FIG. 25

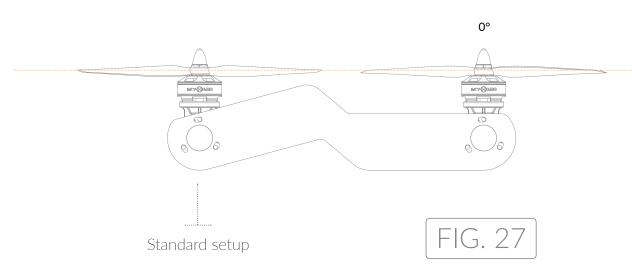


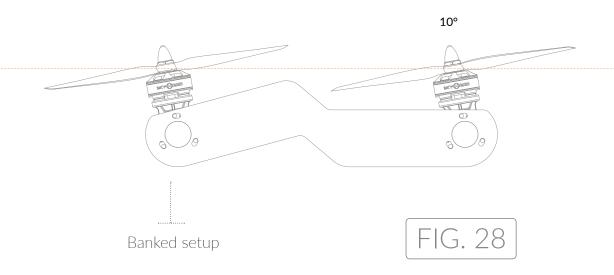
^{*} Optional parts

ADJUST MOTORS ANGLE

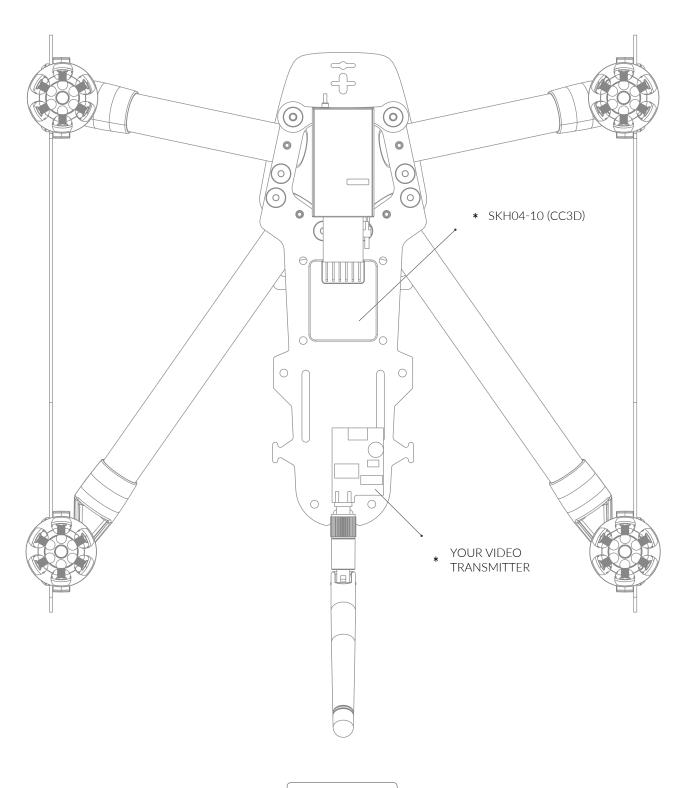
To adjust motor angle to banked position, you need to untight the plactic ring or alu ring on the side and tilt The motor mounts until the edge of the sideframes*.

*You need optional sideframes in order to do this. Check accessories in the Anakin section of our website (www.sky-hero.com) to order them or run to the closest Sky-Hero dealer!





EQUIPMENTS LAYOUT



^{*} Optional parts

